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# Efficient single image dehazing by modifying the dark channel prior



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## Abstract

Outdoor images can be degraded due to the particles in the air that absorb and scatter light. The produced degradation generates contrast attenuation, blurring, and distortion in pixels, resulting in low visibility. These limit the efficiency of computer vision systems such as target tracking, surveillance, and pattern recognition. In this paper, we propose a fast and effective method, through modification in the computation of the dark channel which significantly reduces the artifacts generated in the restored images presented when using the ordinary dark channel. According to our experimental results, our method produces better results than some state-of-the-art methods in both efficiency and restoration quality. The processing time in tests shows that the method is adequate for images with high-resolution and real-time video processing.

**Keywords:** Dark channel prior, Defogging, Dehazing, Image enhancement, Single-image dehazing

## 1 Introduction

The presence of environmental disturbances such as haze and smog gives outdoor images and videos undesirable characteristics that affect the ability of computer vision systems to detect patterns and perform an efficient feature selection and classification. These characteristics are caused by the decrease in contrast and color modification originated by the presence of suspended particles in the air. Hence, the task of removing the haze, fog, and smog (dehazing), without compromising the image information, takes on special relevance. Therefore, to improve the performance of systems such as surveillance [1], traffic [2], self-driving vehicles [3] is essential to develop new and better dehazing methods. This problem has been studied extensively in the literature with two main approaches: methods that use multiple images [4] and methods that use just a single image [1].

Within the single-image approach, some results can be mentioned relevant results, such as the obtained by Tan et al. [5], Fattal [6], and Tarel et al. [7] where the main problem of these proposed methods is the time processing

required and that the proposed methods are not based on solid physics concepts. The most studied method in the literature is presented by He et al. [8] where the dark channel prior (DCP) is introduced. The DCP is a simple but effective approach in most cases, although it produces artifacts around regions where the intensity changes abruptly. Usually, in order to eliminate the artifacts, a refinement stage is necessary, which has an impact on time processing [1, 9]. To get around this problem, He et al. [8] uses a soft-matting process, Gibson et al. [10] proposed a DCP method based on the median operator. Zhu et al. [11] introduced a linear color attenuation prior, and Ren et al. [12] used a deep multiscale neural network.

This paper presents a fast novel method in which a modified dark channel is introduced, improving the quality of the depth estimations of the image elements and reducing significantly the artifacts generated when the traditional dark channel is used. The modification of the proposed dark channel, unlike most state-of-the-art methods, makes a refinement stage unnecessary; this has a positive impact on the simplicity and speed of the dehazing process. Experimental results demonstrate the effectiveness of the proposed method, and when compared with three state-of-the-art methods, the proposed method achieves a higher restoration quality and requires significantly less time. The paper is organized as follows.

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In Section 2, the image degradation model and the dark channel prior used is discussed. The proposed method is presented in Section 3. In Section 4, experimental results and analysis are shown. The conclusions are described in Section 5.

## 2 Background

Based on the atmospheric optic model [1], the formation of a pixel in an *rgb* digital image  $I$  can be described as:

$$I(x, y) = J(x, y)t(x, y) + A(1 - t(x, y)), \quad (1)$$

where  $x, y$  is a pixel position,  $I(x, y) = (I^R(x, y), I^G(x, y), I^B(x, y))$  is the *rgb* observed pixel, and  $A = (A^R, A^G, A^B)$  is the global *rgb* environmental airlight.  $t(x, y)$  is the transmission of scattered light, in an homogeneous medium, which can be described as:

$$t(x, y) = e^{-\beta d(x, y)}, \quad (2)$$

where  $\beta$  is a constant associated with the weather condition, and  $d(x, y)$  is the depth of the scene of every  $x, y$  of  $I$ . Finally,  $J(x, y) = (J^R(x, y), J^G(x, y), J^B(x, y))$  is the value of a pixel with position  $x, y$  of an image  $J$  which has the information of the scene without affectations. Then, to recover  $J(x, y)$ , Eq. 1 can be expressed as:

$$J(x, y) = \frac{I(x, y) - A}{t(x, y)} + A \quad (3)$$

The difficulty in recovering the image  $J$  that lies in that both  $t$  and  $A$  parameters are unknown. In [8], a very useful tool for computing the unknown variables is presented: the dark channel (DC). The DC is defined as:

$$I^{dark}(x, y) = \min_{c \in (R, G, B)} \left( \min_{z \in \Omega(x, y)} I^c(z) \right), \quad (4)$$

where  $\Omega(x, y)$  is a squared window of size  $l \times l$  defined as:

$$\Omega(x, y) = I^c(x - k, y - k) \quad (5)$$

where  $k = \left( \left[ -\left\lfloor \frac{l}{2} \right\rfloor \dots \left\lfloor \frac{l}{2} \right\rfloor \right], k \in \mathbb{N} \right)$ , in this paper the size  $l$  of  $\Omega(x, y)$  used is 15. The dark channel prior (DCP) consists of the following statement: In a non-sky region, the dark channel of a haze free region has a low value, i.e.:

$$I^{dark}(x, y) \rightarrow 0 \quad (6)$$

To compute  $t(x, y)$ , in [8], the Eq. 1 is normalized according to the airlight  $A$  by:

$$\frac{I(x, y)}{A} = \frac{J(x, y)}{A}t(x, y) + 1 - t(x, y) \quad (7)$$

Applying the dark channel in both sides of the Eq. 7:

$$\begin{aligned} \min_{c \in (R, G, B)} \left( \min_{z \in \Omega(x, y)} \frac{I(x, y)}{A}(z) \right) = \\ \min_{c \in (R, G, B)} \left( \min_{z \in \Omega(x, y)} \frac{J(x, y)}{A}(z) \right) \\ t(x, y) + 1 - t(x, y), \end{aligned} \quad (8)$$

since  $J(x, y)$  is the haze-free image, then:

$$J^{dark}(x, y) = \min_{c \in (R, G, B)} \left( \min_{z \in \Omega(x, y)} \frac{J(x, y)}{A}(z) \right) = 0 \quad (9)$$

Substituting Eq. 9 in Eq. 8:

$$\min_{c \in (R, G, B)} \left( \min_{z \in \Omega(x, y)} \frac{I(x, y)}{A}(z) \right) = 1 - t(x, y), \quad (10)$$

then the relation between the dark channel and the transmission  $t$  is:

$$\begin{aligned} t(x, y) = 1 - w \min_{c \in (R, G, B)} \left( \min_{z \in \Omega(x, y)} \frac{I(x, y)}{A}(z) \right) \\ = 1 - wI^{dark}(x, y), \end{aligned} \quad (11)$$

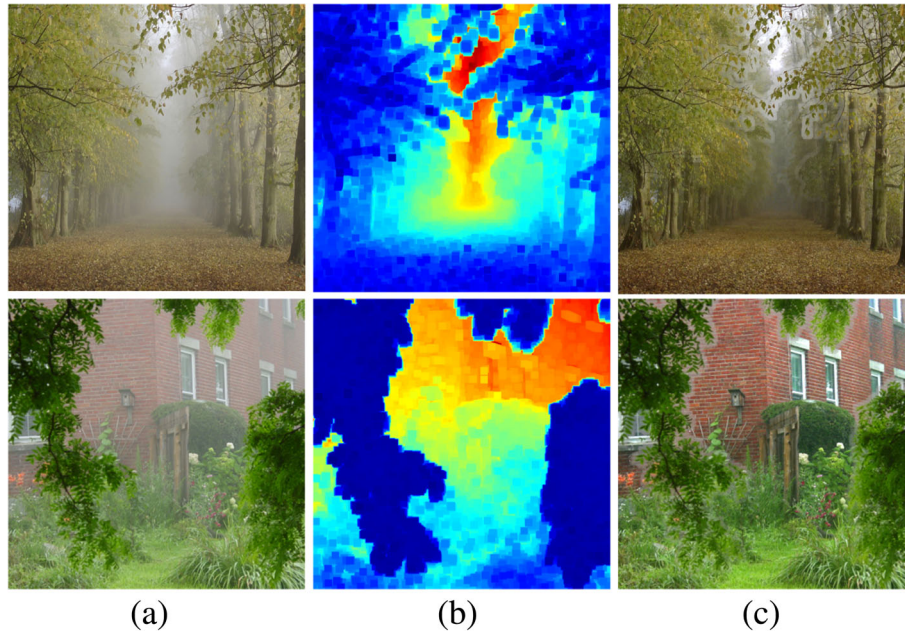
where  $w = [0 \dots 1]$  is a parameter that establishes the recovery level; in [8], the value used was  $w = 0.95$ . In this paper, the best value  $w$  for our method was defined empirically as 0.85. In [8], the airlight  $A$  is considered constant in all the image and is estimated by first selecting the 0.01% of the map generated when the dark channel is computed. From the selected pixels, the one with the highest intensity in the input image  $I$  is selected, and that value is assigned to  $A$ . If the dark channel prior is used to restore an image, the results obtained have artifacts around the edges of the images as it is shown in Fig. 1.

To avoid or reduce the artifacts, the literature proposes the addition of a transmission refinement stage, as is shown in the Fig. 2. The refinement stage increases the processing time requirements of the method, so avoiding the refinement stage is important. In this paper, the modification of the dark channel makes unnecessary the refinement stage.

## 3 The proposed method

### 3.1 The modified dark channel

To illustrate the cause of the artifacts generated when the dark channel prior is applied, the Fig. 3 shows an analysis of the consequences if the dark channel is used directly to restore the image. In Fig. 3a the input image  $I$  is displayed with two windows  $\Omega_1(p_1)$  and  $\Omega_2(p_2)$  with size  $l = 3$ , which are centered in the pixels  $p_1$  and  $p_2$  respectively. Whereas the window  $\Omega_1(p_1)$  is contained in a homogeneous area, the window  $\Omega_2(p_2)$  is in a region near (according to the size of  $\Omega_2$ ) to an edge. In Fig. 3b, it is shown the expected dark channel where the pixels  $p_1$  and  $p_2$  have different values since they belong to different regions. In Fig. 3c, it is shown the dark channel obtained using Eq. 4 where the value of pixel  $p_1$  is correctly estimated; however, the pixel  $p_2$  has a lower value than the expected value; this is because at least one element of the pixels in the window  $\Omega_2(p_2)$  is lower than the pixel  $p_2$ . This is the cause of the generation of artifacts near the edges when the image  $J(x, y)$  is recovered (Fig. 3d).

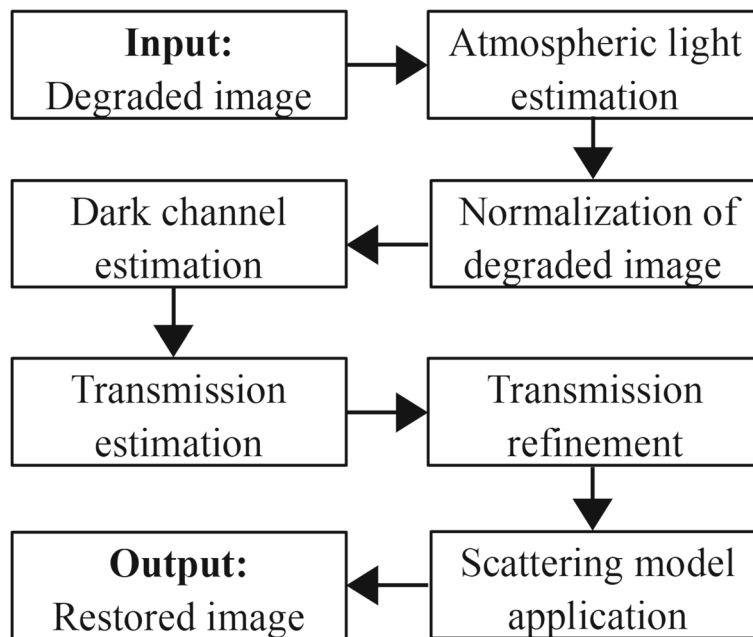


**Fig. 1** Result of recovery an image using the dark channel prior. **a** Hazy input. **b** Dark channel map. **c** Result

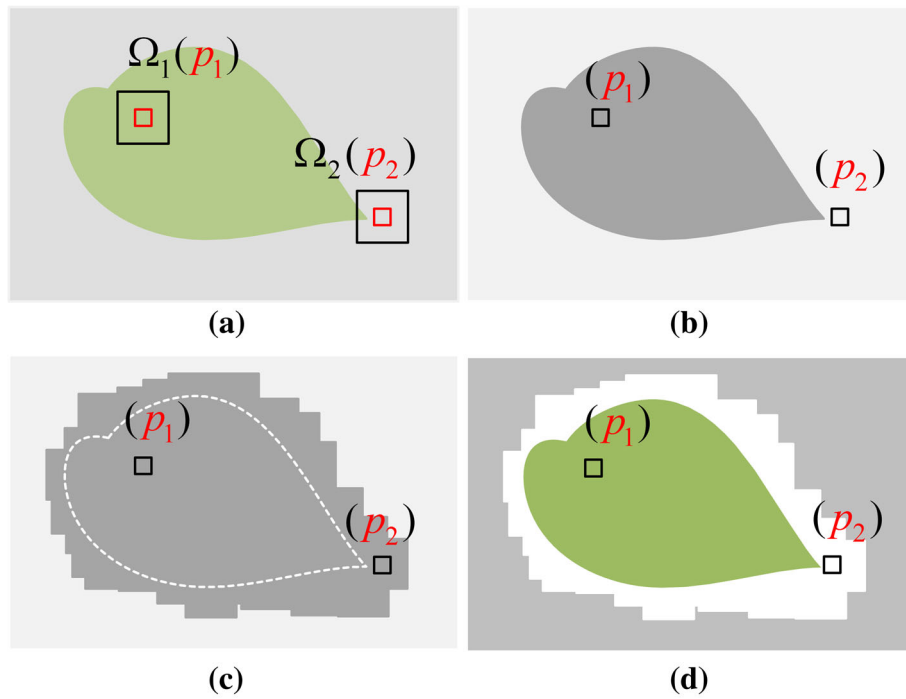
In order to reduce the artifacts, in this paper is proposed a novel approach to incorporate the values obtained from the dark channel. In the proposed approach, initially  $I^{dark}$  is a one channel image with the same size of  $I$  and all the elements  $I^{dark}(x, y)$  are zero. We define  $\alpha$  as a square window with size  $l$  where all its elements has the value of  $I^{dark}(x, y)$  computed according to Eq. 4. Then:

$$I^{dark}_{(x-\lfloor l/2 \rfloor \dots x+\lfloor l/2 \rfloor, y-\lfloor l/2 \rfloor \dots y+\lfloor l/2 \rfloor)} = \text{pixel-wise max}(\alpha_{(1\dots l), (1\dots l)}, I^{dark}_{(x-\lfloor l/2 \rfloor \dots x+\lfloor l/2 \rfloor, y-\lfloor l/2 \rfloor \dots y+\lfloor l/2 \rfloor)}) \tag{12}$$

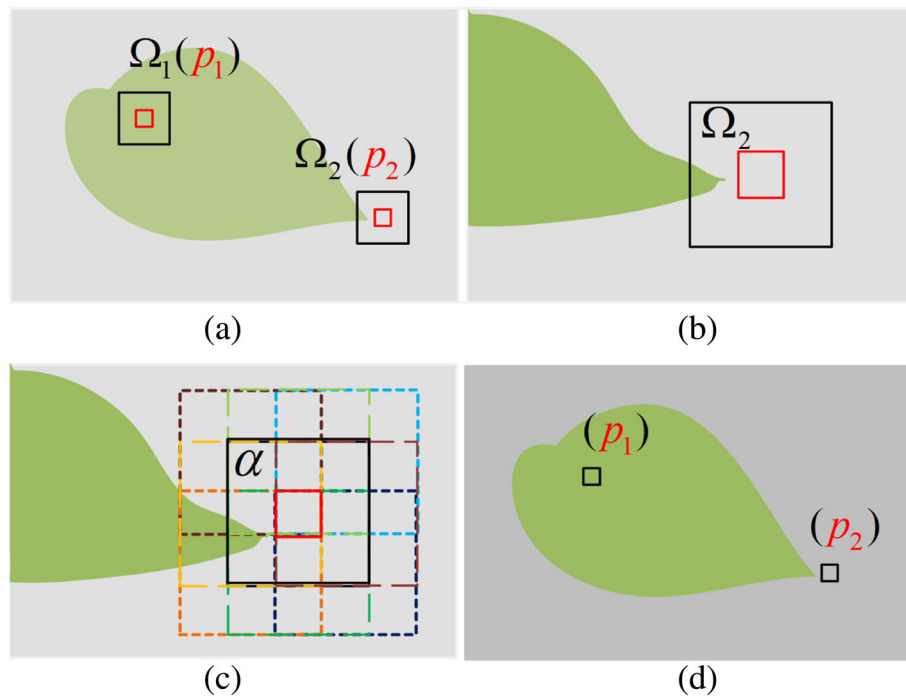
In Fig. 4, a comparison of the information used for any pixel  $(x, y)$ , between classic DC and the modified DC for  $l = 3$ , is displayed.



**Fig. 2** Flowchart of the method based on the dark channel prior proposed in [8]



**Fig. 3** Analysis of the classic DCP algorithm. **a** Input image. **b** Expected dark channel. **c** Obtained dark channel. **d** Recovered image using **c**



**Fig. 4** Analysis of the modified DC. **a** Input image. **b** Information in which the classic DC algorithm is based. **c** Information in which the proposed DC algorithm is based. **d** Recovered image using **c**



The modified dark channel is described in Algorithm 1.

Figure 5 shows an example of the results obtained using the modified DC, where the artifacts in the results have greatly reduced in comparison with the classic DC presented in Fig 1. The pixel-wise maximum operation in the proposed modified DC permits have information about the previous assignment in  $I^{dark}$  in the neighborhood of any pixel  $(x, y)$ . In heterogeneous regions (near from edges), a more robust and precise computation of the DC estimation is obtained because the underestimated values are reduced with the pixel-wise maximum operation. In homogeneous regions (far from edges), the impact of the pixel-wise maximum operation values is practically unmodified because in these regions the neighbors  $I^{dark}$  are quite similar.

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#### Algorithm 1 Modified dark channel

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1: procedure COMPUTEDC( $I, l$ )
2:    $I^{dark} = \text{zeros}(\text{size}(I));$ 
3:   for each  $(x, y)$  in  $I$  do
4:      $\alpha = \text{ones}(l, l) * \min_{z \in \Omega(x, y)} (\min_{c \in (R, G, B)} I^c(z));$ 
5:      $I^{dark}(x - \lfloor l/2 \rfloor : x + \lfloor l/2 \rfloor, y - \lfloor l/2 \rfloor : y + \lfloor l/2 \rfloor) =$ 
6:       pixel-wise  $\max(\alpha(1 : l), (1 : l),$ 
7:        $I^{dark}(x - \lfloor l/2 \rfloor : x + \lfloor l/2 \rfloor, y - \lfloor l/2 \rfloor : y + \lfloor l/2 \rfloor))$ 
8:   end for
9:   return  $I^{dark};$   $\triangleright$  The computed dark channel
10: end procedure

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#### 3.2 Analysis of the image size with the performance of recover images

The DC is a consequence of an empirical observation in outdoor images. Since in the classical and modified DC the size  $l$  of  $\Omega(x, y)$  is constant but the size of the input images are not, we make an analysis of the relation between the size of  $I$  and the performance of the dehazing task. To perform the analysis, two versions of the proposed method were developed: The first one is based on the method shown in Fig. 2, where the computation of the classic DC is substituted by the modified DC. The second method is a variation shown in Algorithm 2, where the variables  $t$  and  $A$  are computed with a resized version of  $I$  called  $I_{nr}$ , where  $nr$  is the new resolution. Next,  $t$  is resized to the original size of  $I$ . Finally, the image is recovered using the scattering model presented in Eq. 1.

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#### Algorithm 2 Dehazing method proposed

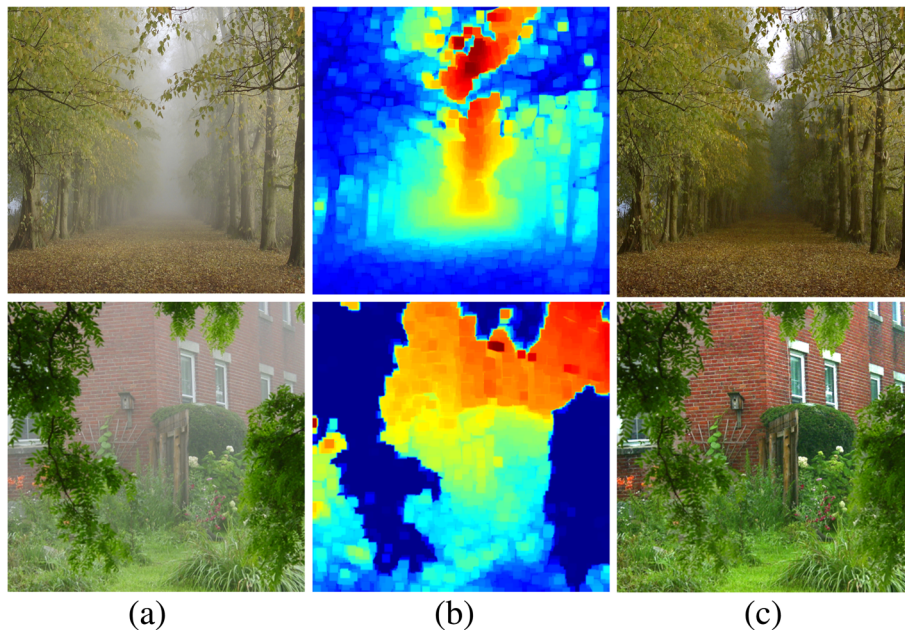
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```

1: procedure PROPOSED( $I, l, \omega, nr$ )
2:    $I_r = \text{resize}(I, nr);$ 
3:    $A = \text{estimateAirLight}(I_r, l);$   $\triangleright$  as in [8]
4:    $I^{dark} = \text{computeDC}(I_r, A, l);$   $\triangleright$  as in Algorithm 1
5:    $t_r = \text{computeTransmission}(I^{dark}, \omega);$   $\triangleright$  Using Eq. 11
6:    $t = \text{resize}(t_r, \text{size}(I))$ 
7:    $J = \text{recoverImage}(I, t, A);$   $\triangleright$  Using Eq. 3
8:   return  $J;$   $\triangleright$  The recovered image
9: end procedure

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**Fig. 5** Result of recovery an image using the modified dark channel prior. **a** Hazy input. **b** Dark channel map. **c** Result

To make the experimental tests, a dataset of 100 images was created using the Middlebury Stereo Datasets [13, 14], in which the haze was simulated with random values of  $t$  and  $A$ . The metric to measure the error used was the Peak Signal-to-Noise Ratio (PSNR). The resolutions  $nr$  tested were  $320 \times 240$ ,  $600 \times 400$ ,  $640 \times 480$ ,  $800 \times 600$ ,  $1280 \times 960$ . The results are shown in Table 1.

Since, according to results of PSNR in Table 1, in our method, the quality of the restored image is not highly affected by the resolution used to compute  $A$  and  $t$ , furthermore, in resolution  $600 \times 400$  the PSNR value is higher, needing a less time processing. Aforementioned, in this paper, the tests are realized with a  $nr$  value of  $600 \times 400$ .

#### 4 Results and discussion

In order to have a reference framework about the performance of the method proposed, a comparison was made against four state-of-the-art methods: the classical DCP method with a soft-matting refinement stage [8], the method that use a median filter to refine the transmission [10], a new approach using an additional prior known as linear color attenuation prior [11], and a method that use a deep neural network [12]. Tests were done using 22 images acquired from two datasets used commonly in the literature: [15], and from [13, 14], in which the affectations were simulated with random values of  $t$  and  $A$ .

It was perform a quantitative analysis using the peak signal-to-noise ratio (PSNR) [16] and the Structural Similarity Index (SSIM) [17]. The PSNR is a quantitative measure of restoration quality between the restored image  $J$  and the target image  $K$ , and it is defined as:

$$\text{PSNR} = 10 \cdot \log_{10} \left( \frac{\max_I^2}{\frac{1}{n} \sum_{(x,y)} (J(x,y) - K(x,y))^2} \right), \quad (13)$$

where  $(x, y)$  is a pixel position,  $n$  is the pixels cardinality of images of  $J$  and  $K$ , and  $\max_I^2$  is the maximum value possible of the images  $J$  and  $K$ , in this case: 255. The Structural Similarity (SSIM) Index is based on a perception model and is described by three aspects comparison, such as:

$$\text{SSIM} = [l, c, s], \quad (14)$$

where  $l$  is the luminance comparison,  $c$  is the contrast comparison, and  $s$  is the structure comparison. The tests were conducted on a computer with a Core i5-2400 processor at 3.10 GHz with 12 GB of RAM using Matlab 2018a.

#### 4.1 Subjective analysis

Figure 6 shows the employed dataset and the results generated by the implemented methods, where it is visible that the proposed method presents a higher contrast and brightness than the other methods.



**Table 1** Comparison in terms of PSNR over 100 synthetic images with different resolutions

Resolution	Original	320 × 240	600 × 400	800 × 600	1280 × 960
PSNR(Db)	19.21	19.01	19.24	19.05	19.19
Time (s)	9.3	1.2	2.1	4.0	10.2

**Table 2** Comparative analysis using the Structural Similarity Index Measure (SSIM)

Image	He et al.	Gibson et al.	Zhu et al.	Ren et al.	Proposed
Aloe	0.116	0.137	0.202	0.162	0.131
Baby1	0.882	0.929	0.949	0.964	0.935
Books	0.912	0.942	0.875	0.939	0.936
Bowling1	0.847	0.862	0.985	0.989	0.951
Cones	0.971	0.938	0.865	0.952	0.932
Dolls1	0.783	0.662	0.577	0.697	0.712
Moebius1	0.945	0.940	0.898	0.948	0.942
Monopoly	0.892	0.928	0.940	0.978	0.944
Reindeer	0.743	0.645	0.579	0.647	0.693
Bikes1	0.762	0.644	0.516	0.596	0.705
Church	0.805	0.853	0.822	0.854	0.823
Couch	0.866	0.818	0.829	0.866	0.850
Dolls	0.833	0.803	0.826	0.834	0.830
Flower1	0.874	0.919	0.945	0.419	0.856
Flower2	0.879	0.864	0.966	0.592	0.838
Mansion	0.914	0.842	0.877	0.873	0.900
Moebius	0.806	0.832	0.939	0.892	0.846
Raindeer	0.837	0.848	0.849	0.799	0.854
Roofs2	0.856	0.781	0.662	0.630	0.814
Trees2	0.732	0.676	0.577	0.612	0.706
Average	0.813	0.793	0.784	0.762	0.810

**Table 3** Comparative analysis using the peak signal-to-noise ratio (PSNR) (in Db)

Image	He et al.	Gibson et al.	Zhu et al.	Ren et al.	Proposed
Aloe	12.02	13.40	14.72	13.86	13.19
Baby1	21.79	21.71	19.27	22.56	21.56
Books	20.49	23.08	17.14	20.51	23.46
Bowling1	15.53	16.29	26.13	28.02	21.44
Cones	26.79	19.99	16.67	22.63	21.05
Dolls1	14.03	10.71	9.46	12.22	12.23
Moebius1	22.89	23.64	18.97	21.91	24.20
Monopoly	16.09	18.74	21.25	21.37	19.12
Reindeer	17.38	12.44	10.34	12.49	15.47
Bikes1	20.68	15.47	12.68	14.36	17.97
Church	12.90	14.00	13.77	15.01	13.17
Couch	18.89	17.41	18.90	19.24	18.21
Dolls	19.09	17.85	16.92	18.93	18.59
Flower1	19.92	20.77	18.80	11.30	19.93
Flower2	18.67	18.62	21.45	13.27	18.42
Mansion	20.11	16.98	18.10	17.86	19.60
Moebius	14.76	15.44	18.54	17.16	15.35
Raindeer	18.73	19.12	20.47	17.45	19.22
Roofs2	21.87	17.51	15.40	13.95	19.49
Trees2	19.57	16.60	13.23	14.29	18.33
Average	18.61	17.49	17.11	17.42	18.50

**Table 4** Comparative analysis of time processing performance (in seconds)

Method	600×400	800×600	1280×720	1920×1080
He et al.	28.9	57.7	128.6	312.1
Gibson et al.	1.7	3.3	6.2	13.6
Zhu et al.	1.05	1.7	3.2	6.7
Ren et al.	2.2	3.8	6.8	13.9
Proposed method	1.9	2.05	1.9	2.1

## 4.2 Objective analysis

PSNR and SSIM metrics were applied to the dataset. Figure 6 presents the dataset with results of the compared algorithms. The Tab. 2 shows that the algorithm according to the SSIM index has an average of 0.81. Table 3 shows a PSNR value of 18.5. The quality performance of our method is just slightly outperformed by the He et al. [8] method. Table 4 shows that our approach outperforms the other methods; particularly, the results of our proposed method is at least 20 times faster than the He et al. [8] method.

## 5 Conclusion

This paper introduces an innovative method which used a variant of the dark channel that greatly reduces the recurrent artifacts presented when using the classic dark channel. Analyzing the experimental results of the quantitative analysis performed, it is observed that the proposed algorithm generates competitive results against four state-of-the-art algorithms without the need for a refinement stage. Because the proposed method has no refinement stage, additionally, it uses a scaled image to compute the variables  $t$  and  $A$  which is faster than state-of-the-art methods. The computation processing time used by the algorithm makes possible its application in high-resolution images and real-time video.

### Abbreviations

DC: Dark channel; DCP: Dark channel prior; PSNR: Peak signal-to-noise ratio; SSIM: Structural Similarity Index

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### Availability of data and materials

We used publicly available data in order to illustrate and test our methods: The datasets used were acquired from [15], and from [13, 14], which can be found in [http://www.cs.huji.ac.il/~raananf/projects/atm\\_light/results/](http://www.cs.huji.ac.il/~raananf/projects/atm_light/results/), and <http://vision.middlebury.edu/stereo/data/> respectively.

### Authors' contributions

All authors took part in the discussion of the work described in this paper. All authors read and approved the final manuscript.



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**Competing interests**

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