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Research Article

Color-Based Image Retrieval Using Perceptually Modified Hausdorff Distance

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In most content-based image retrieval systems, the color information is extensively used for its simplicity and generality. Due to its compactness in characterizing the global information, a uniform quantization of colors, or a histogram, has been the most commonly used color descriptor. However, a cluster-based representation, or a signature, has been proven to be more compact and theoretically sound than a histogram for increasing the discriminatory power and reducing the gap between human perception and computer-aided retrieval system. Despite of these advantages, only few papers have broached dissimilarity measure based on the cluster-based nonuniform quantization of colors. In this paper, we extract the perceptual representation of an original color image, a statistical signature by modifying general color signature, which consists of a set of points with statistical volume. Also we present a novel dissimilarity measure for a statistical signature called Perceptually Modified Hausdorff Distance (PMHD) that is based on the Hausdorff distance. In the result, the proposed retrieval system views an image as a statistical signature, and uses the PMHD as the metric between statistical signatures. The precision versus recall results show that the proposed dissimilarity measure generally outperforms all other dissimilarity measures on an unmodified commercial image database.

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1. INTRODUCTION

With an explosive growth of digital image collections, content-based image retrieval (CBIR) has been emerged as one of the most active and challenging problems in computer vision as well as multimedia applications. Content-based image retrieval differs from the traditional text-based image retrieval in that images would be indexed by the visual features, such as color, texture, and shape [1–3]. In order to reflect the human perception precisely, there have been lots of image retrieval systems, which are based on the query-byexample scheme, including QBIC [4], PhotoBook [5], VisualSEEK [6], and MARS [7]. Actually, low-level visual contents do not properly capture human perceptual concepts, so closing the gap between them is still one of the ongoing problems. However, a series of psychophysical experiments reported that there is a significant correlation between visual features and semantically relevant information [8]. Based on these findings, many techniques have been introduced to improve the perceptual visual features and dissimilarity measures, which enable to achieve semantically correct retrieval performances [1, 9–14].

Among variety of visual features, color information is the most frequently used visual characteristic. Color histogram (or fixed-binning histogram) is widely employed as a color descriptor due to its simplicity of implementation and insensitivity to similarity transformation [9, 15]. However, in some cases, these simple histogram-based indexing methods fail to match perceptual (dis)similarity [16]. Moreover, since the color histogram is sensitive to the variation in color distribution, the performances of these methods usually depend severely on the quantization process in color space. To overcome these drawbacks, a clustering-based representation, signature (or adaptive-binning color histogram) has been proposed [12–14, 16–21]. Based on the psychophysical fact that at the first perception stage the human visual system identifies the dominant colors and cannot simultaneously perceive a large number of colors [12], cluster-based techniques generally extract dominant colors and their proportions to describe the overall color information. Also, a signature represents a set of clusters compactly in a color space and the distribution of color features. Therefore, it can reduce the complexity of representation and the cost of retrieval process.

Once two sets of visual features, represented by a histogram or a signature, are given, we need to determine how similar one is from the other. A number of different dissimilarity measures have been proposed in various areas of computer vision. Specifically for histograms, Jeffrey divergence, histogram intersection, and χ^2 -statistics have been known to work successfully. However, these dissimilarity measures cannot be directly applied to signatures. As alternatives to these metrics, Rubner and Tomasi [16] proposed a novel dissimilarity measure for matching signatures, the Earth Mover's distance (EMD), which was able to overcome most of the drawbacks in histogram-based dissimilarity measures and handle the partial matching between two images. Dorado and izquierdo [17] also used the EMD as a metric to compare fuzzy color signatures. However, the computational complexity of the EMD is very high compared to other dissimilarity measures. Leow and Li [19] proposed a new dissimilarity measure called weighted correlation (WC) for signatures, which is more reliable than Euclidean distance and computationally more efficient than EMD. Generally, WC produced better performance than that of EMD, however in some cases, it showed worse results than those of the Jeffrey divergence (JD) [22]. Mojsilović et al. [12] introduced perceptual color distance metric, optimal color composition distance (OCCD), which is based on the optimal mapping between the dominant color components with area percentage of two images.

In this paper, we extract the compact representation of an original color image, a statistical signature by modifying general color signature, which consists of the representative color features and their statistical volume. Then a novel dissimilarity measure for matching statistical signatures is proposed based on the Hausdorff distance. The Hausdorff distance is an effective metric for the dissimilarity measure between two sets of points [23–25], that is also robust to the outliers and geometric variations in certain degree. Recently, it has been applied to video indexing and retrieval [26]. However, it was simply designed for color histogram model. To overcome this drawback, we propose a new perceptually modified Hausdorff distance (PMHD) as a measure of dissimilarity between statistical signatures, that is consistent with human perception. Moreover, to cope with the partial matching problem, a partial PMHD metric is designed by incorporating outlier detection scheme. The experimental results on a real image database show that the proposed metric outperforms other conventional dissimilarity measures.

This paper is organized as follows. In Section 2, we introduce a statistical signature as a color descriptor. Section 3 proposes a novel dissimilarity measure, PMHD, and partial PMHD for partial matching. Then, Section 4 presents the experimental results and discussions on the effectiveness of the proposed metric. Finally, conclusions are drawn in Section 5.

2. A COLOR IMAGE DESCRIPTOR: A STATISTICAL SIGNATURE

In order to retrieve visually similar images to a query image using color information, a proper color descriptor for the images should be designed. Recently, it has been proven that a signature can describe the color distribution more efficiently than a color histogram [16, 17, 19]. And a signature is appropriate for describing each image independently of other images in an image database.

In this paper, we represent an original color image by a *statistical signature* defined as

$$\mathcal{S} = \left\{ \left(\mathbf{s}_i, w_i, \sum_i \right) \mid i = 1, \dots, N \right\}, \tag{1}$$

where N is the number of clusters, \mathbf{s}_i is the mean feature vector of ith cluster, w_i is the number of the features that belong to ith cluster, and Σ_i is the covariance matrix of ith cluster. Variety of different clustering methods can be used to construct a statistical signature from a color image. In this paper, we used k-means algorithm [27] to cluster color features in CIELab color space.

Figure 1 shows two sample images quantized by using the proposed statistical signature. We could observe that not much perceptual color degradation has occurred, regardless of a great amount of representation data reduction in color space by the clustering.

3. A NOVEL DISSIMILARITY MEASURE FOR A STATISTICAL SIGNATURE

3.1. Hausdorff distance

It has been shown that the Hausdorff distance (HD) is an effective metric for the dissimilarity measure between two sets of points in a number of computer vision literatures [23–25, 28], while insensitive to the variations and noise.

In this section, we briefly describe the HD. More details can be found in [23–25, 28]. Given two finite point sets, $\mathcal{P}_1 = \{p_1^1, \dots, p_N^1\}$ and $\mathcal{P}_2 = \{p_1^2, \dots, p_M^2\}$, the HD is defined as

$$D_{\mathcal{H}} = (\mathcal{P}_1, \mathcal{P}_2) = \operatorname{Max} \left\{ d_H(\mathcal{P}_1, \mathcal{P}_2), d_H(\mathcal{P}_2, \mathcal{P}_1) \right\}, \quad (2)$$

where

$$d_{H}(\mathcal{P}_{1}, \mathcal{P}_{2}) = \max_{p_{1} \in \mathcal{P}_{1}} \min_{p_{2} \in \mathcal{P}_{2}} ||p_{1} - p_{2}||, \tag{3}$$

and the function d_H is the directed HD between two point sets.

3.2. Perceptually modified Hausdorff distance

In this paper, we propose a novel dissimilarity, called perceptually modified Hausdorff distance (PMHD) measure based on HD for comparison of statistical signatures.

Given two statistical signatures, $\mathcal{S}_1 = \{(\mathbf{s}_i^1, w_i^1, \Sigma_i^1) \mid i = 1, ..., N\}$ and $\mathcal{S}_2 = \{(\mathbf{s}_j^2, w_j^2, \Sigma_j^2) \mid j = 1, ..., M\}$, a novel dissimilarity measure between two statistical signatures is defined by

$$\mathcal{D}_{\mathcal{H}}(\mathcal{S}_1, \mathcal{S}_2) = \operatorname{Max}\left\{d_H(\mathcal{S}_1, \mathcal{S}_2), d_H(\mathcal{S}_2, \mathcal{S}_1)\right\}, \tag{4}$$

where $d_H(\mathcal{S}_1, \mathcal{S}_2)$ and $d_H(\mathcal{S}_2, \mathcal{S}_1)$ are directed Hausdorff distances between two statistical signatures.







FIGURE 1: Sample images quantized using k-means clustering: (a) original image with 256 758 colors, and quantized images based on a random signature with (b) 10 colors, and (c) 30 colors.

The directed Hausdorff distance is defined as

$$d_{H}(\mathcal{S}_{1},\mathcal{S}_{2}) = \frac{\sum_{i} \left[w_{i}^{1} \times \min_{j} \left(d(\mathbf{s}_{i}^{1}, \mathbf{s}_{j}^{2}) / \min(w_{i}^{1}, w_{j}^{2}) \right) \right]}{\sum_{i} w_{i}^{1}},$$
(5)

where $d(\mathbf{s}_i^1, \mathbf{s}_j^2)$ is the distance between two color features, \mathbf{s}_i^1 and \mathbf{s}_j^2 in \mathcal{S}_1 and \mathcal{S}_2 , respectively. In this paper, we consider three different distances for $d(\mathbf{s}_i^1, \mathbf{s}_j^2)$: the Euclidean distance, the CIE94 color difference, and the Mahalanobis distance. In order to guarantee that the distance is perceptually uniform, the CIE94 color difference equation is used instead of the Euclidean distance in CIELab color space [29, 30]. While the Euclidean distance and the CIE94 simply measure the geometric distance between two feature vectors in the Euclidean coordinates without considering the distribution of color features, the Mahalanobis distance explicitly considers the distribution of color features after clustering process [31]. Three distances are defined as follows.

(i) Euclidean distance:

$$d_E(\mathbf{s}_i^1, \mathbf{s}_j^2) = \sqrt{\sum_{k=1}^{3} [\mathbf{s}_i^1(k) - \mathbf{s}_j^2(k)]^2},$$
 (6)

where $\mathbf{s}_i^1(k)$ and $\mathbf{s}_i^2(k)$ are the kth elements of \mathbf{s}_i^1 and \mathbf{s}_i^2 , respectively.

(ii) CIE94 color difference:

$$d_{\text{CIE94}}(\mathbf{s}_{i}^{1}, \mathbf{s}_{j}^{2}) = \left[\left(\frac{\Delta L^{*}}{k_{L} S_{L}} \right)^{2} + \left(\frac{\Delta C^{*}}{k_{C} S_{C}} \right)^{2} + \left(\frac{\Delta H^{*}}{k_{H} S_{H}} \right)^{2} \right]^{1/2},$$

$$S_{L} = 1, S_{C} = 1 + 0.045 \Delta C^{*}, S_{H} = 1 + 0.015 \Delta C^{*},$$

$$k_{L} = k_{C} = k_{H} = 1,$$

$$(7)$$

where ΔL^* , ΔC^* , and ΔH^* are the differences in lightness, chroma, and hue between \mathbf{s}_i^1 and \mathbf{s}_i^2 .

(iii) Mahalanobis distance:

$$d_M(\mathbf{s}_i^1, \mathbf{s}_j^2) = (\mathbf{s}_j^2 - \mathbf{s}_i^1)^T \sum_{i=1}^{j-1} (\mathbf{s}_j^2 - \mathbf{s}_i^1).$$
 (8)

Note that in order to take into account the size of clusters in matching, we penalize the distance between two color feature vectors by the minimum of their corresponding sizes as in (5). This reflects the fact that color features with a large size influence more the perceptual similarity between images than the smaller ones [12]. Let us consider an example as in Figure 2(a). There are two pairs of feature vectors denoted by circles centered at the mean feature vectors. The radius of each circle represents the size of the corresponding feature. If we compute only the geometric distance without considering the size of two feature vectors, two distances d_1 and d_2 will be equal. However, perceptually d_2 must be smaller than d_1 . Another example is given in Figure 2(b), where three feature vectors are shown. Again, if we consider only the geometric distance, d_1 will be smaller than d_2 . However, in fact, perceptual d_2 is smaller than d_1 .

Thus, by combining the set theoretical metric and perceptual notion in the dissimilarity measure, the proposed PMHD becomes relatively insensitive to the variations of mean color features in a signature, and consistent with human perception.

3.3. Partial PMHD metric for partial matching

In certain cases, a user may have a partial information of the target images as the query, or wants to extract all the images including partial information of the query. In these cases, conventional techniques with global descriptor are not appropriate. Like a color histogram, a signature is also a global descriptor of a whole image. So, the direct application of the HD as in (4) cannot cope with occlusion and clutter in image retrieval or object recognition [16, 28, 32]. In order to handle partial matching, Huttenlocher et al. [23] proposed a partial HD based on ranking, which measures the difference between portions of point sets. Also, Azencott et al. [25] further modified the rank-based partial HD by order statistics. But, these distances were shown to be sensitive to the parameter changes. In order to address these problems, Sim et al. [28] proposed two robust HD measures, M-HD and LTS-HD, based on the robust statistics such as M-estimation and least trimmed square (LTS). Unfortunately, they are not appropriate for image retrieval system because they are computationally too complex to search a large database.

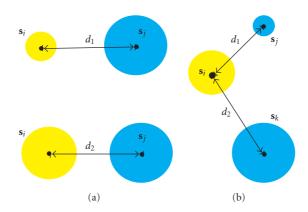


FIGURE 2: An example of perceptual dissimilarity based on the densities of two color features.

In this paper, in order to remedy the partial matching problem, we detect and exclude the outliers first by an outlier test function, and then apply the proposed PMHD to the remaining feature points. Let us define the outlier test function by

$$f(i) = \begin{cases} 1, & \min_{j} \frac{d(\mathbf{s}_{i}^{1}, \mathbf{s}_{j}^{2})}{\min(w_{i}^{1}, w_{j}^{2})} < Dth, \\ 0, & \text{otherwise,} \end{cases}$$
 (9)

where Dth is a prespecific threshold for the outlier detection. The above function indicates that \mathbf{s}_i^1 is inlier if f(i) = 1, otherwise outlier.

Now let us define two directed Hausdorff distances with and without outliers by

$$\begin{split} d_{H}^{a}(\mathcal{S}_{1},\mathcal{S}_{2}) &= \frac{\sum_{i} w_{i}^{1} \times \min_{j} \left(d(\mathbf{s}_{i}^{1},\mathbf{s}_{j}^{2}) / \min(w_{i}^{1},w_{j}^{2}) \right)}{\sum_{i} w_{i}^{1}}, \\ d_{H}^{p}(\mathcal{S}_{1},\mathcal{S}_{2}) &= \frac{\sum_{i} w_{i}^{1} \times \min_{j} \left(d(\mathbf{s}_{i}^{1},\mathbf{s}_{j}^{2}) / \min(w_{i}^{1},w_{j}^{2}) \right) \times f(i)}{\sum_{i} w_{i}^{1} \times f(i)}, \end{split}$$

respectively.

Then the new modified directed partial PMHD is obtained by

$$d_{H}(\mathcal{S}_{1}, \mathcal{S}_{2}) = \begin{cases} d_{H}^{a}(\mathcal{S}_{1}, \mathcal{S}_{2}), & \frac{\sum_{i} w_{i}^{1} \times f(i)}{\sum_{i} w_{i}^{1}} > P \text{th,} \\ d_{H}^{b}(\mathcal{S}_{1}, \mathcal{S}_{2}), & \text{otherwise,} \end{cases}$$
(11)

where *P*th is a prespecific threshold for the control of a faction of information loss.

4. EXPERIMENTAL RESULTS

4.1. The database and queries

To evaluate the retrieval precision and recall performance of the proposed retrieval system, several experiments have been conducted on a real database. We used 5200 images selected from commercially available Corel color image database without any modification. There are 52 semantic categories, each of them containing 100 images. Among those, we have chosen four sets of data including Cheetah, Eagle, Pyramids, and Royal guards as the query. Some example images in the queries are shown in Figure 3. We note in Figure 3 that since the original categorization of images was not based on the color information, substantial amount of variations in color still exist even in the same category. Nonetheless, in this experiment, we used all images in these four categories as queries. We computed a precision and recall pair to all query categories, which is commonly used as the retrieval performance measurement [33]. The precision *P* and recall *R* are defined as

$$P = \frac{r}{n}, \qquad R = \frac{r}{m},\tag{12}$$

where r is the number of retrieved relevant images, n is the total number of retrieved images, and m is the total number of relevant images in the whole database. The precision P measures the accuracy of the retrieval and the recall R measures the effectiveness of the retrieval performance.

4.2. Retrieval results for queries

The performance of the proposed PMHD was compared with five well-known dissimilarity measures, including *histogram intersection (HI)*, χ^2 -statistics, *Jeffrey divergence (JD)*, and *quadratic form (QF) distance*, for the fixed binning histogram, and *EMD* for the signature.

Let H_1 and H_2 represent two color histograms or signatures. Then, these five dissimilarity measures are defined as follows.

(1) Histogram intersection (HI) [34]:

$$d(H_1, H_2) = 1 - \frac{\sum_i \min(h_i^1, h_i^2)}{\sum_i h_i^2},$$
 (13)

where h_i^j is the number of elements in the *i*th bin of H_i

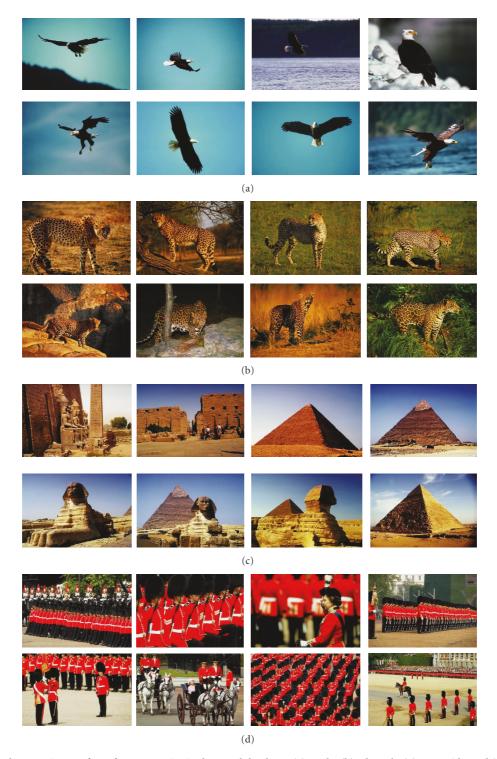


FIGURE 3: Example query images from four categories in the Corel database. (a) Eagle, (b) Cheetah, (c) Pyramids, and (d) Royal guards.

(2) χ^2 -statistics:

(3) Jeffrey divergence (JD) [22]:

$$d(H_1, H_2) = \sum_{i} \frac{(h_i^1 - m_i)^2}{m_i}, \qquad (14) \qquad d(H_1, H_2) = \sum_{i} \left(h_i^1 \log \frac{h_i^1}{m_i} + h_i^2 \log \frac{h_i^2}{m_i}\right), \qquad (15)$$

where $m_i = (h_i^1 + h_i^2)/2$.

where again $m_i = (h_i^1 + h_i^2)/2$

(4) Quadratic form (QF) distance [4, 35]:

$$d(H_1, H_2) = \sqrt{(H_1 - H_2)^T A (H_1 - H_2)}, \tag{16}$$

where *A* is a similarity matrix that encodes the crossbin relationships based on the perceptual similarity of the representative colors of the bins.

(5) EMD [16, 36]:

$$d(H_1, H_2) = \frac{\sum_{i,j} g_{ij} d_{ij}}{\sum_{i,j} g_{ij}},$$
(17)

where d_{ij} denotes the dissimilarity between the ith and jth bins, and g_{ij} is the optimal flow between two distributions. The total cost $\sum_{i,j} g_{ij} d_{ij}$ is minimized subject to the constraints,

$$g_{ij} \ge 0, \quad \sum_{i} g_{ij} \le h_j^2, \quad \sum_{j} g_{ij} \le h_i^1,$$

$$\sum_{i,j} g_{ij} = \min\left(\sum_{i} h_i^1, \sum_{j} h_j^2\right).$$
(18)

As reported in [36], EMD yielded a very good retrieval performance for the small sample size, while JD and χ^2 performed very well for the larger sample sizes. Leow and Li [19] proposed the novel dissimilarity measure, weighted correlation (WC) which can be used to compare two histograms with different binnings. In the image retrieval, the performance of WC was comparable to other dissimilarity measures, but not good as JD. Therefore, in this paper, we evaluated only the performance of JD.

In order to represent a color image as a fixed histogram representation, the RGB color space was uniformly partitioned into $10 \times 10 \times 10 = 1000$ color bins. And a color was quantized to the mean centroid of the cubic bin. While, as mentioned in Section 2, a statistical signature was extracted by applying K-means clustering. To compare the performance of the signature-based dissimilarity with other fixed histogram-based ones, the quantization level was matched by clustering a color image into only 10 color feature clusters. The mean color quantization error of the $10 \times 10 \times 10$ -bin histogram is 5.99 CIE94 units and that of quantized imagebased on a statistical signature containing 10 color feature vectors was 5.26 CIE94 units. It is noted that the difference between two quantized image errors are smaller than the perceptibility threshold of 2.2 CIE94 units [37], where two colors are perceptually indistinguishable [19]. The performance of retrieval results of the proposed metric and other dissimilarity measures are summarized by the precision-recall in Figure 4. It is noted that the proposed PMHD dissimilarity measure significantly outperformed other dissimilarity measures for all query images. The performance of PMHD is, on average, 20-30% higher than the second highest precision rate over the meaningful recall values. And the performance of PMHD with Euclidean distance is almost the same as that of PMHD with CIE94, and usually performed best in the image retrieval. It is somewhat surprisingly noted that EMD performed poorer than other dissimilarity measures in all query categories except "Eagle." This is not coincident

TABLE 1: The best parameters for partial matching: (*Dth*, *Pth*).

| Query | Distances | | |
|--------------|-------------|-----------|----------|
| | Mahalanobis | Euclidean | CIE94 |
| Eagle | (50,0.6) | (50,0.7) | (50,0.8) |
| Cheetah | (80,0.8) | (90,0.9) | (90,0.9) |
| Pyramids | (100,0.7) | (50,0.6) | (30,0.6) |
| Royal guards | (30,0.6) | (100,0.9) | (40,0.6) |

with the results reported in [16, 36], where EMD performed very well for the small sample sizes and compact representation but not so well for large sample sizes and wide representation. As indicated in [19], the image size, the number of color features in a signature, and the ground distance may degrade the whole performance of EMD. However, as mentioned before, we only used a signature with 10 color features in this experiment, which is a very compact representation. We note that the large image size of 98 304 pixels or so and the Euclidean ground distance may severely degrade the performance of EMD.

4.3. Dependency on the number of color features in a signatures

In general, the quantization level of a color space, that is, the number of clusters in a signature or the number of bins in the fixed histogram, has an important effect on the overall image retrieval performance. In order to investigate the effect of the level of quantization, we examined the performance of the proposed method according to the number of color features in a signature. In this experiment, two quantization levels of 10 and 30 are compared. In addition, the results showed that the mean color error of 30 color features case was 3.38 CIE94 units, which was much smaller than 5.26 CIE94 units, that of the statistical signature with 10 color features. Figures 1(b) and 1(c) show two sample quantized images of Figure 1(a) by 10 and 30 colors, respectively. It is noted that the quantized image with 30 color features is almost indistinguishable from the original image that contains 256 758 color features.

Figure 5 plots the precision-recall curves of the image retrieval results according to the number of color features in a signature. We compared the retrieval performance of the proposed PMHD with EMD, since EMD was the only dissimilarity measure applicable to signatures. The precision rate of EMD did not vary significantly as the number of color features of a signature increased, as depicted in Figure 5. However, the precision rates of PHMD (especially with the Euclidean and CIE94 distances) with 30 color features became higher than that of PMHD with 10 color features. From this result, we can expect that the performance of the proposed PMHD gets better as the quantization error decreases. Moreover, this implies that PMHD performs especially well for the large sample sizes as well as the compact representation.

4.4. Partial matching

In order to assess the performance of the proposed partial PMHD, the same four queries in Figure 3 have been used.

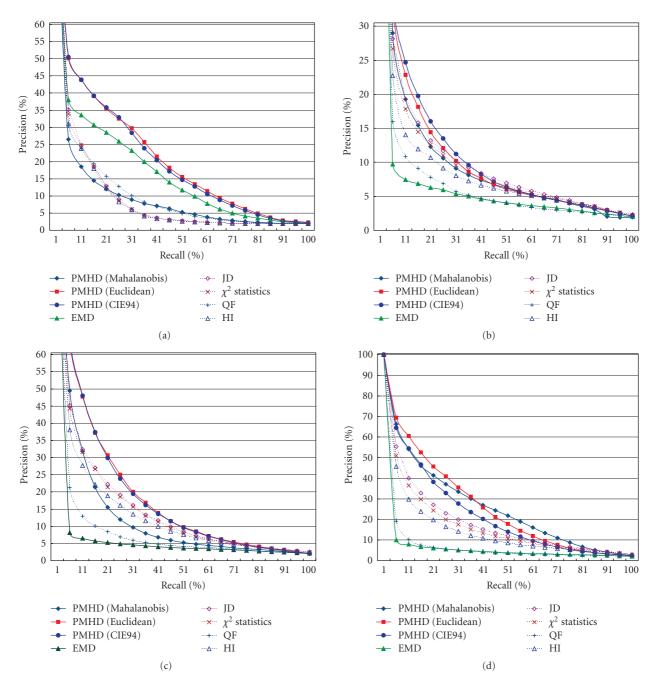


FIGURE 4: Precision-recall curves for various dissimilarity measures on four query categories: (a) Eagle, (b) Cheetah, (c) Pyramids, and (d) Royal guards.

The precision-recall performance has been obtained by varying two parameters, *D*th and *P*th. Figure 6 plots the best performances and the used parameters are shown in Table 1.

It is noted that although the differences between retrieval performances of two metrics were not significantly large, at most 10% in the case of Eagle, the performance of the partial PMHD mostly outperformed that of full PMHD.

There are some problems in employing the partial PMHD. First, as can be noted in Table 1, it is difficult to get appropriate parameters automatically that can be adopted to all queries. The values of parameters severely depend on the

type of query. Second, the performance of the partial PMHD can be more worse than that of the PMHD in high recall rate, as shown in Figure 6(a). Moreover, the complexity of the partial PMHD is a little high compared to that of the PMHD. Thus, in order to exploit the advantages of the partial PMHD for CBIR, these drawbacks should be made up for properly.

5. CONCLUSION

In this paper, we proposed a novel dissimilarity measure for color signatures, perceptually modified Hausdorff distance

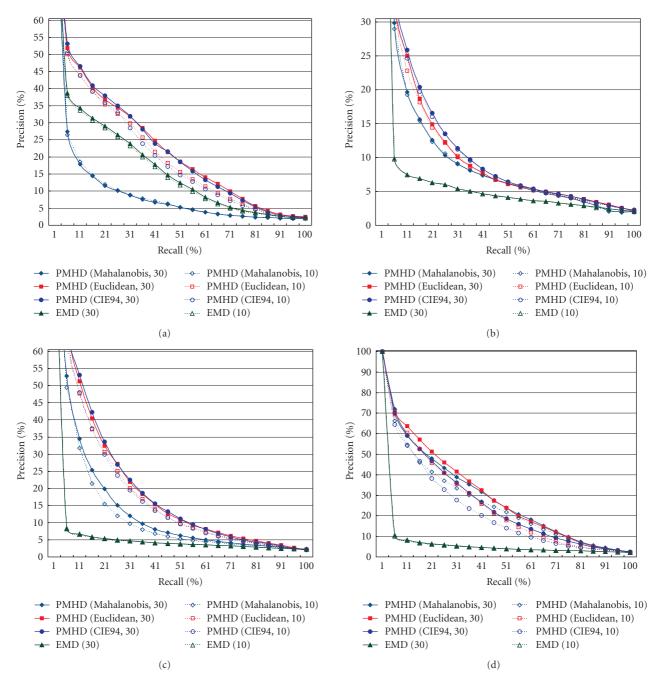


FIGURE 5: Comparison of the retrieval performance for varying the number of color features in a signature: (a) Eagle, (b) Cheetah, (c) Pyramids, and (d) Royal guards.

(PMHD) based on Hausdorff distance. PMHD is insensitive to the characteristics changes of mean color features in a signature, and theoretically sound for incorporating human perception in the metric. Also, in order to deal with partial matching, the partial PMHD was defined, which explicitly removed outlier using the outlier detection function.

The extensive experimental results on a real database showed that the proposed PMHD outperformed other conventional dissimilarity measures. The retrieval performance of the PMHD is, on average, 20–30% higher than the second highest one in precision rate. Also the performance of the

partial PMHD was tested on the same database. Although there were some unresolved problems including high complexity and finding optimal parameters, the performance of the partial PMHD mostly outperformed that of PMHD and showed great potential for general CBIR applications.

In this paper, we have used only the color information for the signature. However, recent studies showed that combining multiple cues including color, texture, scale, and relevance feedback can improve the results drastically and close the semantic gap. Thus, combining these multiple information in a multiresolution framework will be our future work.

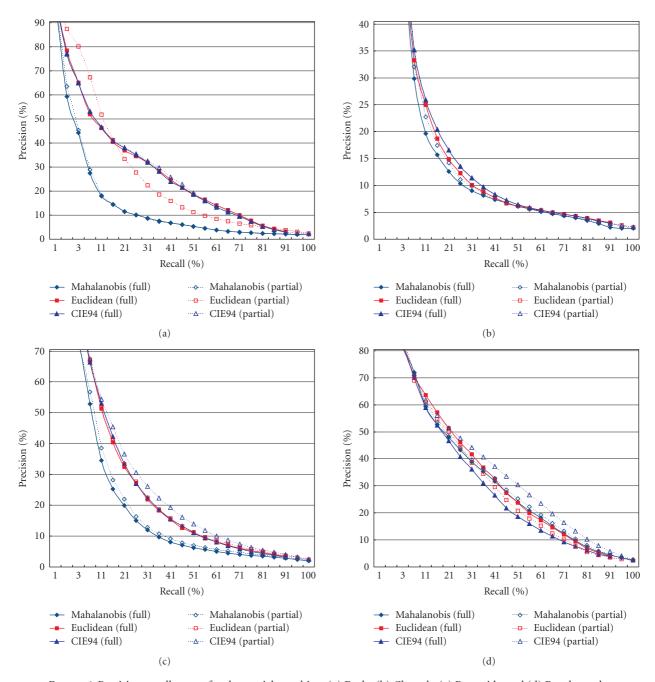


FIGURE 6: Precision-recall curves for the partial matching: (a) Eagle, (b) Cheetah, (c) Pyramids, and (d) Royal guards.

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